

# Embedded Linux development training 3 days session

Title	Embedded Linux development training	
Overview	<ul> <li>Understanding the Linux kernel</li> <li>Building the Linux kernel</li> <li>Developing with Yocto Project</li> <li>Developing Linux device drivers</li> <li>Linux application debugging</li> <li>Working with the kernel development community</li> <li>Practical labs with ARM-based board</li> </ul>	
Duration	three days - 24 hours (8 hours per day).50% of lectures, 50% of practical labs (approx.)	
Trainer	Marco Cavallini m.cavallini (AT) koansoftware.com	
Language	Oral lectures: English or Italian Materials: English.	
Audience	People developing devices using the Linux kernel People supporting embedded Linux system developers.	
Prerequisites	Knowledge of embedded Linux as covered in our embedded Linux training (http://koansoftware.com/en/content/linux-embedded-	



Required equipment	<ul> <li>For public sessions</li> <li>Everything is supplied by KOAN in public sessions except the PC.</li> <li>Participants must have their own PC laptop computer with: <ul> <li>USB3 port support (for Disk provided) We will use a 32GB USB3 disk to work with Lubuntu 12.04 (32 bit)</li> <li>USB to power the target board</li> <li>USB to connect the serial adapter (provided)</li> <li>Ethernet connector (for communication with the target)</li> <li>Wifi</li> <li>PC computers with valuable data must be backed up before being used in our sessions. Some people have already made mistakes during our sessions and damaged work data.</li> </ul> </li> <li>For on-site sessions please add the following <ul> <li>Video projector</li> <li>Connection to the Internet (direct or through the company proxy).</li> </ul> </li> </ul>
Materials	Print and electronic copies of presentations and labs. Electronic copy of lab files.

#### Hardware

The hardware platform used for the practical labs of this training session is the **BeagleBone Black** board, which features:

- An ARM AM335x processor from Texas Instruments (Cortex-A8 based), 3D acceleration, etc.
- 512 MB of RAM
- 4 GB of on-board eMMC storage (4 GB in Rev C)
- USB host and device
- HDMI output
- 2 x 46 pins headers, to access UARTs, SPI buses, I2C buses



Note: The order and the content of the following program may vary slightly



### Day 1 - Morning

Lecture - Setup and Introduction			
<ul> <li>Virtual machine setup</li> <li>Introduction to embedded linux</li> <li>Advantages of using linux</li> <li>Systems running linux</li> <li>Typical embedded hardware</li> <li>System architecture</li> </ul>			
Lecture - Linux commands and Cross compilation	Lab - Using linux		
<ul> <li>Toolchain components</li> <li>Understanding the development process</li> <li>C libraries</li> </ul>	<ul> <li>Using the Virtual Machine</li> <li>Using the Unix command line</li> <li>Using the vi text editor</li> <li>Using the apt package manager</li> </ul>		

- C libraries
- Toolchain options

• Discovering procfs and sysfs

## Day 1 - Afternoon

Lecture - Configuring, compiling and	Lab - Kernel configuration, cross-
booting the Linux kernel	compiling and booting on NFS
<ul> <li>Embedded linux development environments</li> <li>Linux kernel features</li> <li>Linux versioning schemes</li> </ul>	<ul> <li>Using the Virtual Machine</li> <li>Get the kernel sources from the official location</li> <li>Check the authenticity of the kernel sources</li> </ul>



### Day 2 - Morning

### Lecture - Yocto Project introduction

Yocto Project overview

Yocto Project meta layers

Yocto Project recipes

• How to setup the Yocto Project build system

#### Lecture - Yocto Project

#### Lab - Running Yocto on the host

Using the Virtual Machine

- Setup a Yocto Project build system
- Creating a meta layer with Yocto Project
- Creating a recipe with Yocto Project

### Day 2 - Afternoon

Lecture - Linux kernel and device drivers Lab - Running linux on the target

- Linux kernel configuration
- Kernel booting parameters.
- Booting the kernel using NFS.
- Native and cross-compilation generated files.

Using the ARM board

- Configure the TFTP and the NFS server
- Flash a Linux image on a SDCard
- Launch the Linux image on your target board
- Play around with Embedded Linux on your board



### Day 3 - Morning

### Lecture - Kernel init and Bootloaders

- Cross-compiling the kernel for the target
- Linux kernel sources structure
- Linux driver development
- Details about the API provided to kernel drivers

#### Lecture - Linux filesystems - Busybox Lab - Device driver

- Kernel initialization
- Bootloaders
- Boot sequence
- u-boot
- Linux root filesystem

### Using the ARM board

- Creating a basic device driver
- Creating a simple character driver

### Day 3 - Afternoon

#### Lecture - Application debugging

- Block filesystems
- Flash filesystems
- Virtual filesystems
- Busybox

#### Lab - Running linux on the target

Using the ARM board

- Debugging user space applications
- Remote debugging user space applications